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Device for automatically filling and packing predetermined weight of product in containers

Abstract:

A kind of automatic rotary weighing and packing machine having a plurality of weighers (1-8) radially or annularly arranged on a circular rotary table (10) for automatically effecting such processes as filling of product, weighing and judgement at respective positions around the table, which is especially suitable in the case where the product to be packed is sticky granular or powdered bulk material and the packing container is a bag or the like. This machine uses no weigh hopper or bucket in which sticky product is liable to remain to cause weight error and the packing container is held by a holding

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mechanism (12) attached to each weigher (1-8) and directly filled with product, which is then weighed and sealed. A fixed amount feeding device (24) is used for feeding product in the container (16) and it is throughout controlled, based upon the result of weighment for keeping the weight of product packed in each container always at a predetermined value.

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54) Device for automatically filling and packing predetermined weight of product in containers.

(57) A kind of automatic rotary weighing and packing machine having a plurality of weighers (1-8) radially or annularly arranged on a circular rotary table (10) for automatically effecting such processes as filling of product, weighing and judgement at respective positions around the table, which is especially suitable in the case where the product to be packed is sticky granular or powdered bulk material and the packing container is a bag or the like. This machine uses no weigh hopper or bucket in which sticky product is liable to remain to cause weight error and the packing container is held by a holding mechanism (12) attached to each weigher (1-8) and directly filled with product, which is then weighed and sealed. A fixed amount feeding device (24) is used for feeding product in the container (16) and it is throughout controlled, based upon the result of weighment for keeping the weight of product packed in each container always at a predetermined value.

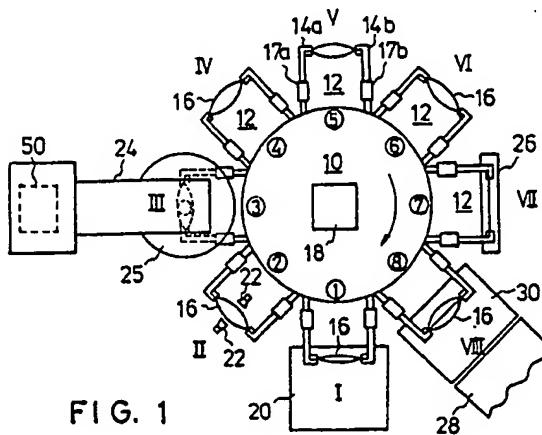


FIG. 1

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Device for Automatically Filling and Packing Predetermined Weight of Product in Containers

This invention relates to an automatic weighing, filling and packing device and, especially, to a rotary weighing, filling and packing machine comprising a rotary table or turret provided with a plurality of weighing beads arranged circularly thereon for automatically and successively effecting such operations as filling, weighing and packing product at respective fixed locations disposed around it.

British Patent No. 1,013 130 discloses an example of such machine according to the prior art. It includes a turret provided with a plurality of weighing heads each having a weigh hopper or basket. A plurality of operating locations are disposed along the periphery of the turret and specific operations are applied to each weighing head when it passes these locations. In the cited example, for instance, a predetermined amount of product is fed to the weighing hopper by an automatic feeder at the first location and a container is fed and filled with the product discharged from the weigh hopper at the last location. At the locations between both locations, the product in the weigh hopper is weighed for generating a weight signal and, based upon this weight signal judgement of acceptability of the packed product and adjustment of the amount of product to be fed are effected.

Although this type of automatic weighing and packing machine is effective when the product is hard and or relatively large grain size and accompanied by no dust, part of product may remain in the weigh hopper to cause an error in the net weight of the packed product when the product is powdered or viscous and, especially, sticky. In order to solve this problem, one may use such a method as weighing product after filling the container. More particularly, it is considered to substitute each weigh hopper with a weighing cradle for putting thereon the container and injecting the product directly therein, as suggested in the British patent publication No. 2,195 779A. However, this system is undesirable when the container has an unstable shape as in the case of a soft bag.

Accordingly, an object of this invention is to provide an improved automatic rotary weighing, filling and packing device which is suitable to bag-like containers and can automatically effect not only accurate measurement of the net weight, but also judgement of acceptability of the product and adjustment of the amount of product to be fed.

This object can be attained by the device of this invention, which comprises a rotary table having a plurality of weighing heads arranged circularly thereon and each provided with a weigher which includes a packing container holding mecha-

nism instead of the weigh hopper. A plurality of operating locations are disposed around the rotary table for applying specific operations to each weighing head which has arrived therat. More particularly, the packing container is fed to and held by the holding mechanism at the first location and the weight of the container is measured and then stored at the second location. The container is filled with a predetermined amount of product from an automatic feeder at the third location and the weight of the filled container is measured and the above-mentioned stored value is subtracted therefrom to obtain net weight which is then compared with a predetermined allowable range to judge its acceptability at the fourth location. The opening of the container is closed at the fifth location and the packed products are sorted and delivered based upon the result of judgement at the sixth location. The above-mentioned automatic feeder is adapted so that its amount of feed can be adjusted automatically based upon the deviation of the net weight from a predetermined target weight.

These and other objects and features of this invention will be more clarified by reading the following description with reference to the accompanying drawings.

Figure 1 is a schematic plan view representing an embodiment of the rotary weighing, filling and packing device according to this invention;

Figure 2 is a side view of the embodiment of Figure 1;

Figure 3 is a perspective view representing a schematic structure of an inventive container holding mechanism included in the embodiment of Figure 1;

Figure 4 is an electric circuit diagram representing a configuration of control system of the embodiment of Figure 1;

Figure 5 is a timing diagram representing time relationship of respective operations applied to each weighing head of the embodiment of Figure 1;

Figure 6 is a schematic plan view representing another embodiment of the rotary weighing, filling and packing device according to this invention; and

Figure 7 is a schematic plan view representing a further embodiment of the rotary weighing, filling and packing device according to this invention.

Referring to Figures 1 and 2, a rotary table 10 which rotates intermittently about a central axis includes eight weighing heads arranged at equal intervals therearound as shown by numerals 1 to 8

enclosed in small circles and each head includes a container holding mechanism 12. As shown in Figure 3 the holding mechanism 12 includes a pair of holding arms 14a and 14b having catching units 15a and 15b at their tops, which are automatically opened and closed by a suitable actuating device (not shown) to hold a bag-like container 16 as shown in phantom. The holding arms 14a and 14b are also provided with load cells 17a and 17b near their roots for sensing the weight of product held by the catching units 15a and 15b to supply a corresponding weight signal to a control device 18 on the table 10. Around the rotary table 10, eight operating locations are settled as shown by Roman numerals I to VIII and the following operations are applied at these locations to each weighing head revolving thereto.

A packing container feeding device 20 is disposed at operating location I at which the bag-like container 16 is automatically fed to the weighing head arriving thereof and held by the holding mechanism 12. Thus, the load cells 17a and 17b generate a weight signal corresponding to the weight of the container namely, the tare. This weight signal is taken into the control device 18 when it becomes stable in the next operating location II and stored in a memory location of a built-in memory corresponding to the weighing head as described later. A suction device 22 is disposed at location II to open the opening of the bag-like container after tare storage. A product feeder 24 having a screw feeder 25 for example is disposed at operating location III, thereby a predetermined amount of product is fed to each container 16. The product feeder 24 may be of any known type, such as electromagnetic vibration type or gravity type, which is suitable to the feature of product to be fed. Then, the load cells 17a and 17b generate a weight signal corresponding to the weight of the filled container and this signal is taken into the control device 18 when it becomes stable at the next operating location IV. An undermentioned central processing unit (CPU) included in the control device 18 subtracts a corresponding tare value stored previously from this weight signal to calculate a net weight and compare it with a preset allowable range. When it does not fall within this range, it generates a failure signal and stores it in a memory location of the memory corresponding to the weighing head. In operating locations V and VI vibration is applied to the holding mechanism 12 to settle the product in the container as occasion demands. In operating location VII, the holding arms 14a and 14b open to the arrow direction of Figure 3 to close the opening of the container 16 and the opening is then sealed by a suitable sealing device 26. The product thus packed is released from the holding mechanism 12 at the last operat-

ing location VIII and delivered through a chute 30 to a transporting device such as belt conveyor 28. The chute 30 is adapted to move as shown in phantom in Figure 2 in response to the failure signal in the corresponding memory location for removing the corresponding product as rejected. The above-mentioned operations are repeated sequentially for each weighing head and acceptable products are delivered successively by the conveyor 28 at operating location VIII.

As shown in Figure 4, the weight signals generated by eight load cells 17-1, 17-2 ... 17-8 each consisting of the above-mentioned pair of halves 17a and 17b are respectively amplified by amplifiers 32-1, 32-2, ... 32-8 included in the control device 18 and sequentially supplied through an analog-to-digital (A/D) convertor 36 to a central processing unit (CPU) 38 by a multiplexer 34 in time-division fashion. The CPU 38 operates based upon an operation program preset in a read-only memory (ROM) in an incorporated memory device 40 a weight condition supplied from a keyboard input device 42 and undermentioned pulse signals from an external sequencer 44 to execute calculation of the net weight of the product of each weighing head and judgement of its acceptability and to write the result thereof in the corresponding memory location of a random-access memory (RAM) of the memory device 40 as described above. The calculated value is supplied through a digital-to-analog (D/A) convertor 46 to a motor control device 48 which controls a motor 50 for driving the screw feeder 25 of the product feeder 24 based upon this value, thereby adjusting the amount of product fed to the container 16 at operating location III. The control device 48 also stops the feed of product in response to a stop signal from the CPU 38 as described above. The CPU 38 also reads the result of judgement from the memory location of RAM corresponding to the weighing head arriving at operating location VIII and supplies it to a sorter driving device 52 which moves the chute 30 to remove the corresponding product to be rejected.

While the intermittent rotation of the rotary table 10 is controlled by a program of the above-mentioned sequencer 44 the sequencer 44 generates an origin recognition pulse signal RP and a timing pulse signal TP as shown in Figure 5 in synchronism with this rotational motion. The pulse RP occurs every rotation of the rotary table 10, that is, every cycle of operation and, in this embodiment, it occurs when the first weighing head 1 coincides with the first operating location I as shown in Figure 1. Thus, each operating cycle is initiated at this position as the origin and CPU 38 is responsive to this signal to recognize it. The timing pulse TP occurs every intermittent motion of the rotary table 10 and, in this embodiment, it occurs

eight times every cycle. This pulse TP has a pulse width t_a equal to the stationary time of the rotary table 10 and a pulse interval t_b equal to the transit time thereof. One cycle of operation is divided into eight steps 1 to 8 as shown by the pulses TP and CPU 38 is adapted to count this pulse by built-in counter for recognizing the relationship between the steps of operation and the respective weighing heads as shown in the lower half of Figure 5.

Considering now the first weighing head 1 existing at the first operating location I in the first step of operation, a container is fed and held by the holding mechanism 12 of this head at this location as described above. Therefore, the weight signal W of the load cell 17-1 of this weighing head increases as shown and then becomes stable at location II in the next step to indicate the weight of the container, that is, the tare value W_0 . CPU 38 is adapted to write the sufficiently stable tare value W_0 in the memory device 40 after a predetermined stationary time t_c of the table 10 as shown. The weight signal W increased abruptly in the third step or at location III since the container is filled with product. CPU 38 compares this signal w with a reference value W_r preset in the memory device 40 and, when coincidence is obtained therebetween, supplies a stop signal to the motor control device 48 to stop the feed of product. The reference value W_r is selected so that the signal W further increases by over-feed and reaches a target value W_t after stopping the feed. The signal W is read by CPU 38 in the fourth step at location IV when it becomes sufficiently stable after the predetermined stationary time t_c of the table 10 as described above, and the tare value W_0 in the memory device 40 is subtracted therefrom to calculate the net weight. Acceptability of this net weight is then judged based upon the predetermined allowable range as described above and a sorting operation is effected based upon the result of judgement at the last eighth step. If necessary, deviation of the calculated net weight from a predetermined value may be calculated for adjusting the above-mentioned reference value W_r based thereupon. This deviation signal may be applied to the motor control device 48 for controlling the amount of feed. These calculating and adjusting operations are completed enough within the time interval of the fourth step and this enables complete correction of the amount of feed to the next (eighth) head. The above-mentioned operations are applied to each weighing head with sequential shift by one step as shown in Figure 5.

As described above, the weight signal W is read by CPU 38 only at the operating locations II, III and IV. Therefore, it is unnecessary for the multiplexer 34 to pass the weight signals from all weighing heads in each step and it is enough to

apply the time division operation selectively to those from only three weighing heads which are underlined in Figure 5. Accordingly, the switching pulses for the multiplexer 34 may be selected so as to fit thereto.

5 The second embodiment of this invention shown in Figure 6 includes a first rotary table 60 having six weighing heads around it and a second rotary table 61 having six holding heads around it. While each weighing head of the first rotary table 60 includes a holding mechanism having a load cell as same as the weighing head of Figure 1 each holding head of the second rotary table 61 includes a holding mechanism having no load cell. 10 As shown in the drawing, nine operating locations I to IX are disposed around the first and second rotary tables and location V is common to both tables. These tables are adapted to rotate synchronously at the same speed so that the heads of both tables get together at operating location V. Container supply, tare measurement, filling and weighing are effected respectively at operating locations I, II, III and IV as in the embodiment of Figure 1 and the filled container is handed over at location V from the holding mechanism of the weighing head to the holding mechanism of the holding head. The product is settled by the aid of vibration at operating locations VI and VII as in location V and VI of the embodiment of Figure 1 and sealing and delivery of the package are effected at respectively at locations VIII and IX as locations VII and VIII of the embodiment of Figure 1. Although such operations as processing of weight data and adjustment of the amount of feed are completely same as those of the embodiment of Figure 1 it has such an advantage that the weighing operation is hardly affected by the vibration at locations VI and VII since the operations after weighing have been transferred to the second table.

20 25 30 35 40 45 50 55 While the third embodiment shown in Figure 7 includes two rotary tables 60 and 61 having six weighing heads and six holding heads respectively as same as the embodiment of Figure 6, a product feeder 62 is carried on the first rotary table 60 so as to rotate therewith. Each weighing head includes a filling nozzle 64 connected to the product feeder 62 and the nozzle is opened and closed by an automatically controlled valve (not shown) at operating location III to supply a predetermined amount of product into the underlying bag-like container. Although the containers are supplied by an automatic rotary feeding device 66 at operating location I in the embodiment as shown, the other operations are completely same as those of the embodiment of Figure 6. However, it is possible in this embodiment to effect the product filling operation across one or both of operating locations II and IV as occasion demands, thereby improving the

operational speed.

While the invention has been described in detail above in connection to the three embodiments, this is only for the illustrative purpose but never means its limitation. It is a matter of course that various modification and changes can be made thereon without leaving the scope of the invention as defined in the appended claims.

Claims

1. A device for automatically filling and packing a predetermined weight of product in containers, comprising a first rotary table including a plurality of weighing heads arranged at equal intervals around said table, each said weighing head including weight detecting elements and a bag-like container holding mechanism, and a plurality of operating means disposed at first to sixth operating locations arranged in this order around said first rotary table for applying specific treatments to each weighing heads passing said locations; characterized by said operating means comprising:
 container feeding means for feeding a bag-like container to said holding mechanism to be held thereby when each said weighing head arrives at said first operating location,
 memory means for reading and storing the weight of said container detected by said weight detecting elements when each said weighing head arrives at said second operating location,
 product feeding means for filling said container with a predetermined target weight of product when each said weighing head arrives at said third operating location
 arithmetic means for subtracting the stored weight of said container from the weight of the filled container detected by said weight detecting elements to calculate the net weight of said product, comparing said net weight with a predetermined allowable range to judge the acceptability thereof and storing the result of judgement when each said weighing head arrives at said fourth operating location
 feed control means for adjusting the amount of feed of said product feeding means based upon the deviation of said net weight from said target weight while each said weighing head exists at said fourth operating location,
 sealing means for sealing the opening of said container to complete a packed product when each said weighing head arrives at said fifth operating location, and
 delivery means for discharging said packed product from said holding mechanism and, if not acceptable, removing said product based upon said stored result of judgement when each said weighing head arrives at said sixth operating location.

2. A device as set forth in claim 1, characterized by a second rotary table provided with a plurality of holding heads being arranged at equal intervals around said table and adapted to rotate in synchronism with said first rotary table, whereby each said holding head gets together with each weighing head of said first rotary table, each said holding head including a bag-like container holding mechanism, transfer means for transferring said container from the weighing head to the holding head when said weighing head gets together with said holding head, at least said first to fourth operating locations being arranged around said first rotary table, and the other operating locations being arranged around said second rotary table.
 3. A device as set forth in Claim 1 or 2, characterized in that said product feeding means is disposed on said first rotary table, whereby enabling said filling operation to be effected during revolution of said weighing heads.
 4. A device as set forth in Claim 1, 2 or 3 characterized in that said operating means further comprises vibrating means for applying vibration to said filled container to settle the product between said fourth and fifth operating locations.
 5. A device as set forth in Claim 1, 2, 3 or 4, characterized in that the container holding mechanism of each said weighing head includes a pair of holding arms which can move close to and apart from each other each said holding arm is provided with a container catching unit at the top thereof and with said weight detecting element near the root thereof whereby said bag-like container fed thereto is caught and hung at both ends of the opening thereof to enable detection of the weight thereof.

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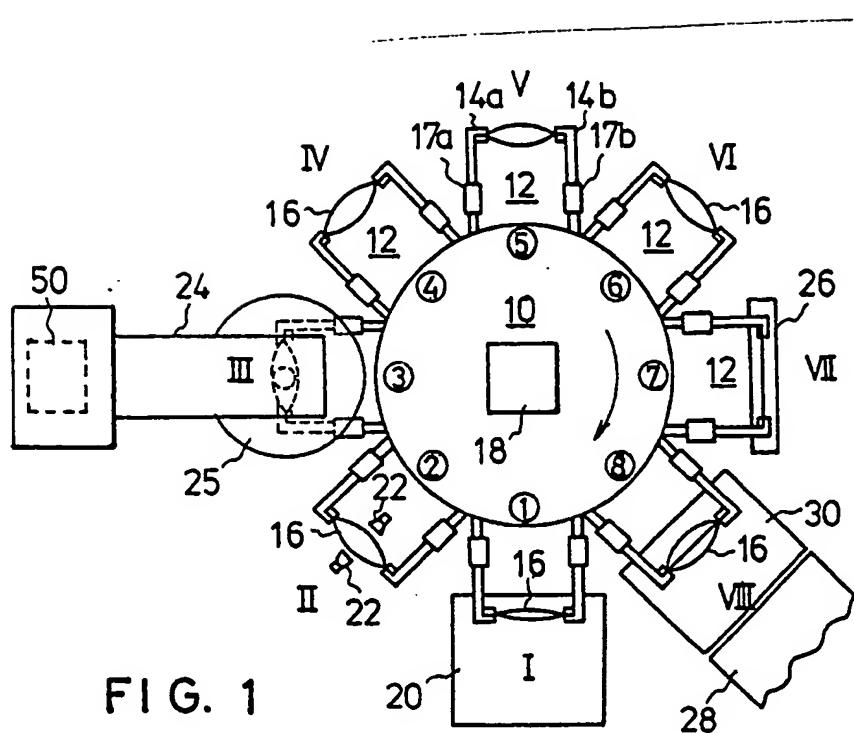


FIG. 1

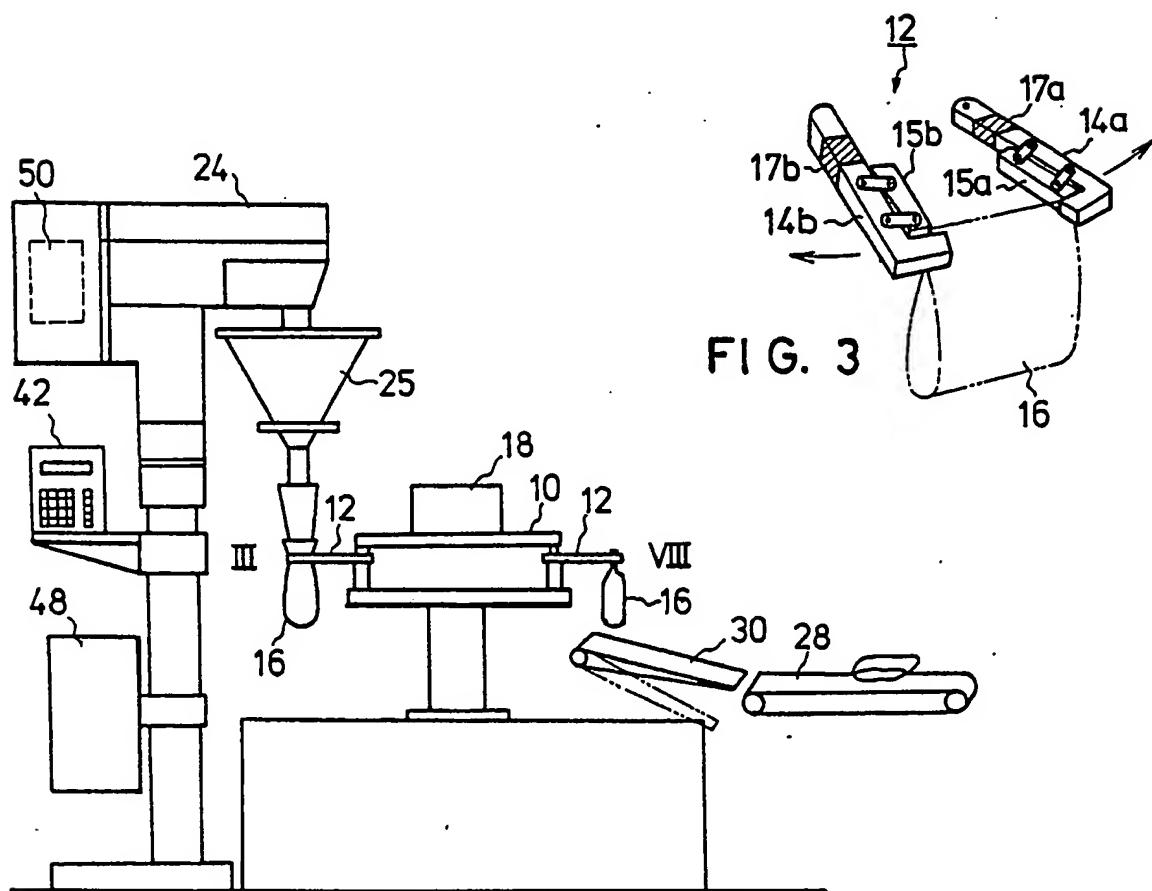


FIG. 2

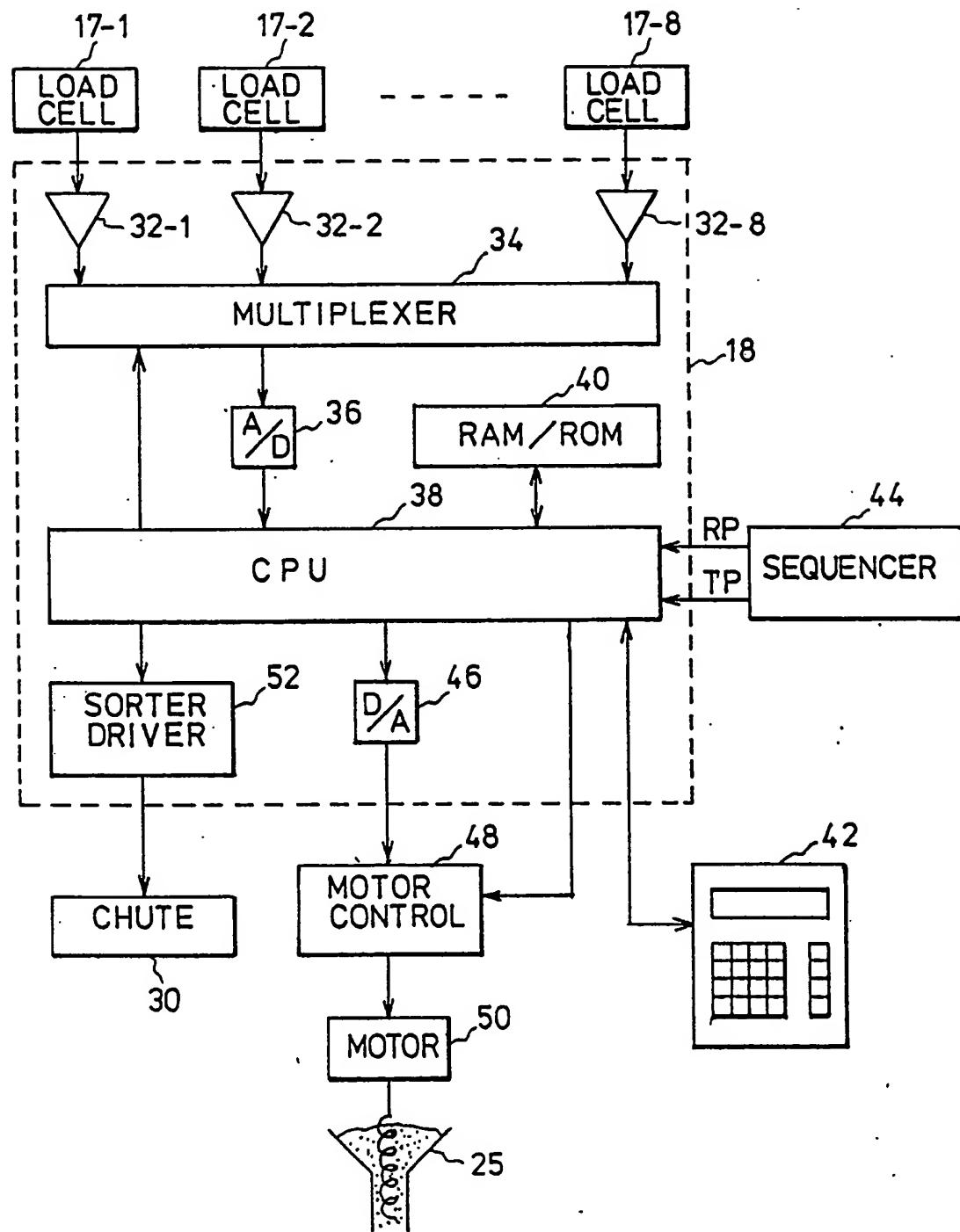
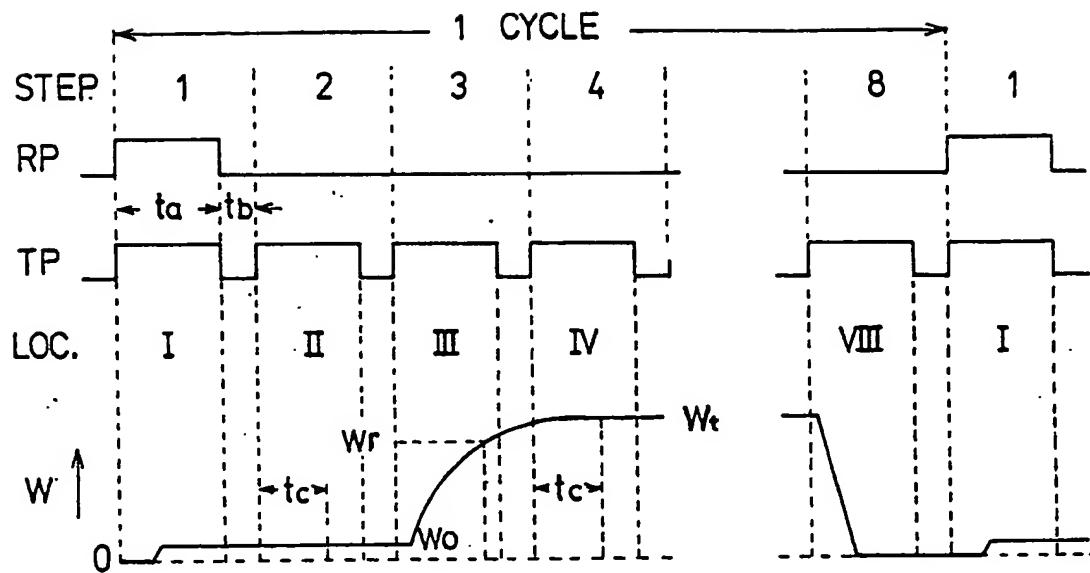


FIG. 4



I	1	8	7	6	2	1
II	2	1	8	7	3	2
III	3	2	1	8	4	3
IV	4	3	2	1	5	4
V	5	4	3	2	6	5
VI	6	5	4	3	7	6
VII	7	6	5	4	8	7
VIII	8	7	6	5	1	8

FIG. 5

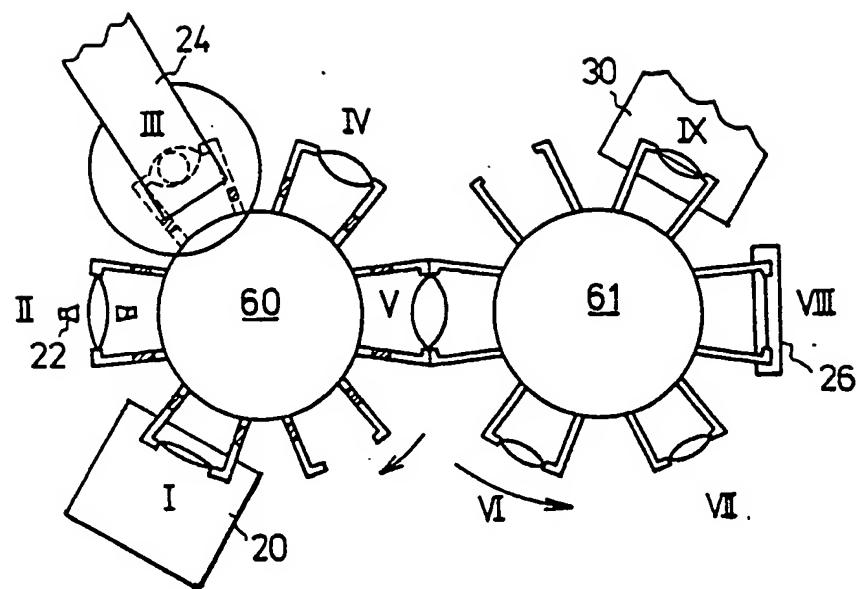


FIG. 6

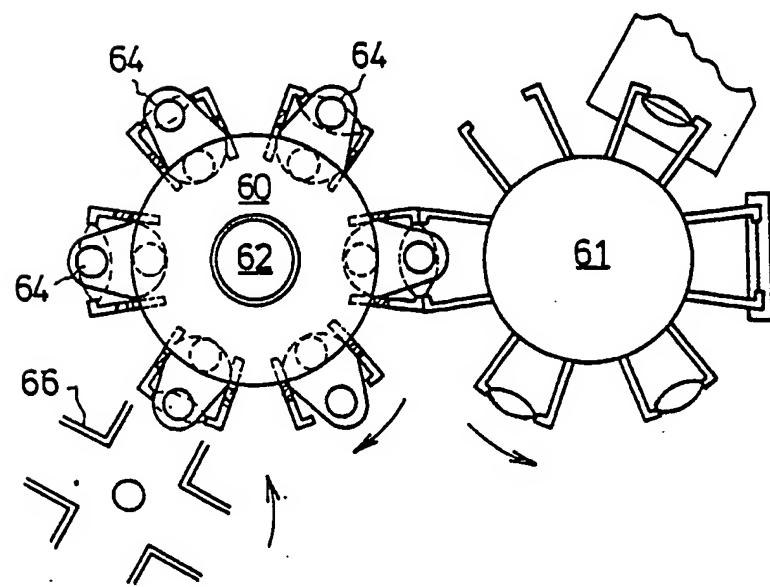


FIG. 7



DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.4)
Y	DE-C-3 639 293 (MVT) * Whole document * ---	1	B 65 B 1/32 B 65 B 43/50
Y	DE-B-1 636 213 (HESSE) * Column 2, lines 3-32; column 3, lines 22-35; figure 1 * ---	1	
A	DE-A-3 425 082 (HAVER & BOECKER) * Page 10; figures 1,2 * ---	1	
A	CH-A- 655 474 (ANSTALT INDUSTRIE BERATUNG) * Page 2, lines 13-37; figure * ---	1,3	
A	GB-A-2 078 191 (BRISTOL PACKAGING) * Page 2, lines 107-109 * ---	4	
A	DE-A-3 503 992 (BOSCH) * Abstract; figure 1 * ---	5	
A	FR-A-2 564 421 (HAVER & BOECHEK) -----		TECHNICAL FIELDS SEARCHED (Int. Cl.4) B 65 B G 01 G
<p>The present search report has been drawn up for all claims</p>			
Place of search	Date of completion of the search	Examiner	
THE HAGUE	15-09-1989	SCHELLE, J.	
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